# **BLASTMAN B16S - Generation 4.0**

## **ROBOT CONFIGURATION**

		Range /m/°	Max. Speed	Type
Axis 1	Main frame horiz.	3 - 50 m	0,3 m/s	Lin.
Axis 2	Robot Arm Vert.	2 - 10m	0,3 m/s	Lin.
Axis 3	Arm rotation	180°	25,2°/s	Rot.
Axis 4	Shoulder	175°	21,5°/s	Rot.
Axis 5	Elbow	225°	19,9°/s	Rot.
Axis 6	Arm head	360°	180°/s	Rot.
Axis 7	Nozzle	270°	215 °/s	Rot.

#### **OPERATION MODES**

Manual (Control room)
Automatic

Parameter based automatic

## **TEACHING METHODS**

Teach In PTP Offline

Parameter based (option)

#### **OPERATIONAL PARAM.**

Nozzle diam. 13 - 19 mm 1/4" - 3/4" No. Of Nozzles 1 or 2 Air Pressure Air Pressure 50 - 150 PSI Cleaning rate  $200 \text{ m}^2\text{/h}$  ....  $2150 \text{ ft}^2\text{/h}$ 



**Voltage** 380-500V 50/60Hz

Contr. voltage 24 VDC Sealing \* IP65

Assembly Wall Mounted Weight \*\* 3000 kg

#### **FEATURES**

#### Control

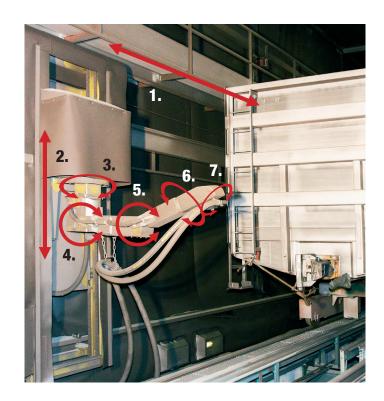
- Manipulator without robot features
- License for software updates
- Offline teaching
- Automatic teaching in offline environment
- VPN connection for remote diagnostics and SW updates
- Remote process monitoring
- Control of blast room machineries

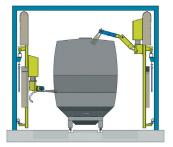
# **Blast equipment**

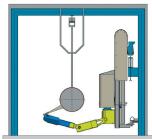
- Complete operational blast room
- Blast pot for robot
- Blast hoses
- Blast nozzles

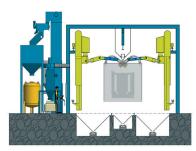
#### **Other**

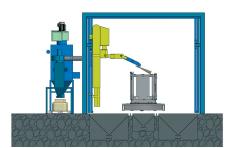
- Rails for the robot
- Transfer car for the workpiece
- Warranty extension
- Installation services











<sup>\*</sup>Applies to electrics in the blast room

<sup>\*\*</sup> Depends on height